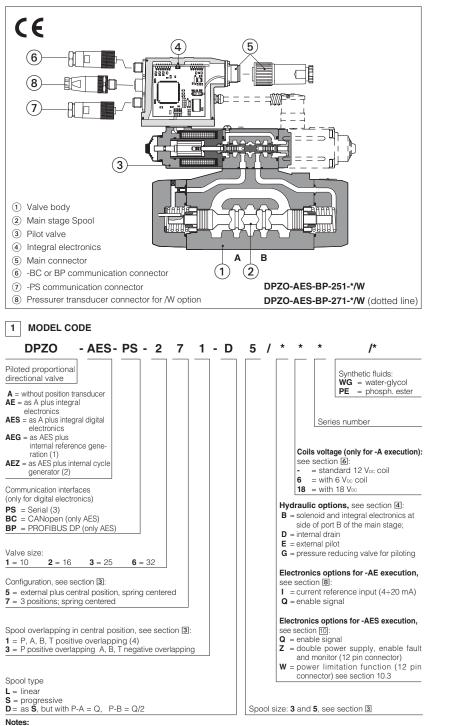


# Proportional directional valves type DPZO-A\*

two stage without position transducer, ISO 4401 sizes 10, 16, 25 and 32



(1) For detailed description of AEG integral reference generation, see tab. G120 For detailed description of AEG integral cycle generation, see tab. C
 For detailed description of AEG integral cycle generation, see tab. G120
 Serial interface always present, also for -BC and -BP options (4) Overlapping = 20% of spool stroke for type S and D, 10% of spool stroke for type L

# 2 ELECTRONIC DRIVERS FOR DPZO-A\*

Valve model				-AE	-AES	-AEG	-AEZ			
Drivers model	E-MI-AC-0*F	E-MI-AS-IR	E-BM-AC-0*F	E-BM-AS-PS	E-ME-AC-0*F	E-RP-AC-0*F	E-RI-AE	E-RI-AES	E-RI-AEG	E-RI-AEZ
Data sheet	G010	G020	G025	G030	G035	G100	G110	G115	G120	G120

Note: For power supply and communication connector see section [17] and [19]

#### DPZO-A\* are two stage proportional valves without position transducer, which provide both directional and non compensated flow control according to the electronic reference signal.

They operate in association with electronic drivers, see section 2, which supply the proportional valves with correct current signal to align valve regulation to the reference signal supplied to the electronic driver

They are available in different executions:

- -Å, without position transducer;
- AE, -AES as -A plus analogue (AE) or digital (AES) integral electronics ⊕;
  -AEG, as AES plus internal reference generation selected by four on-off (0÷24VDC) inputs available on the main connector (see tab. G120).
- -AEZ, as AES plus internal cycle generation for automatic control of actuator's motion cycle (see tab. G120).

The 4-way spool ②, sliding into a 5chambers body (1), is piloted in open loop by the proportional pressure reducing valve (3) type DHRZO.

The integral electronics ④ ensures factory presetting, fine functionality plus valve-tovalve interchangeability and simplified wiring and installation.

The electronic main connector (5) is fully interchangeable for -AE and -AES executions

Standard 7 pin main connector is used for power supply, analog input reference and monitor signals.

12 pin connector is used for -AEG, -AEZ versions and for option /Z (AES)

Following communication interfaces (6), (7) are available for the digital -AES, -AEG and -AEZ executions:

- standard -PS, Serial communication interface for configuration, monitoring and firmware updating through Atos PC software - always present
- optional -BC, CANopen interface (only for -AES)
- optional -BP, PROFIBUS DP interface (only for -AES)

The valves with -BC and -BP interfaces can be integrated into a fieldbus communication network and thus digitally operated by the machine control unit.

The coils are fully plastic encapsulated (insulation class H) and valves have antivibration, antishock and weather-proof features

Surface mounting: ISO 4401 size 10, 16, 25 and 32.

Max flow respectively up to 160 l/min, 340 I/min, 680 I/min and 1030 I/min with valve differential pressure  $\Delta p = 30$  bar, see section 3

Max pressure: 350 bar.

# 3 HYDRAULIC CHARACTERISTICS (based on mineral oil ISO VG 46 at 50 °C)

Hydraulic symbols *71			*7	3		*51			\$53		*5	1/B		*53/B
						∎ b								
Valve model		DPZO-1				DPZO-2				DPZO-3	-3 DPZO-6			;
Spool overlapping		1, 3				1, 3			1, 3			1, 3		
Spool type and size	L5	S5	D5	S3	D3	L5	S5	D5	L5	S5	D5	L5	S5	D5
Max flow (1) [l/min]														
at $\Delta p = 10$ bar (P-T)	100	100	100:60	130	130:80	200	180	180:130	390	360	360:220	600	600	600:370
at $\Delta p = 30$ bar (P-T)	160	160	160:100	225	225:135	340	310	310:225	680	620	620:380	1030	1030	1030:640
max permissible flow	180	180	180:110	500	500:300	710	640	640:460	1350	1250	1250:760	1600	1600	1600:100
Pressure limits (2) [bar]				рс	rts P, A, E	3, X = 35	ю; T =	250 (5 fc	r option	/D); Y	= 5			
Response time [ms]	< 80				< 100						< 120			
Hysteresis [%]		≤ 5%												
Repeatability							±	1%						

Notes:

• For version DPZO-A and DPZO-AE, configuration /B, see the notes at section 14.1

• Above performance data refer to valves coupled with Atos electronic drivers, see section 2.

• In case of long time shutdown of the hydraulic supply to the pilot valve, the driver has to be switched off to avoid its overheating.

• The flow regulated by the directional proportional valves is not pressure compensated, thus it is affected by the load variations. To keep costant the regulated flow under different load conditions, modular pressure compensators are available (see tab. D150).

(1) For different  $\Delta p$ , the max flow is in accordance to the diagrams in section 14.2

(2) Minimum piloting pressure = 30 bar

# 4 HYDRAULIC OPTIONS

4.1 Option /B Solenoid (for valve configuration \*5\*) and integral electronics at side of port A. For hydraulic configuration vs. reference signal, see section 14.1

4.2 Pilot and drain configuration -The pilot / drain configuration can be modified as shown in the table E080 section 12.

- The valve's standard configuration provides internal pilot and external drain. For different pilot / drain configuration select:
- Option /E External pilot (through port X). Option /D Internal drain.
- **Option /G** Pressure reducing valve with fixed setting (= 40 bar for DPZO-1 and -2; 100 bar for DPZO-3) installed between pilot valve and main body. It is advisable for valves with internal pilot in case of system pressure higher than 200 bar.

# 5 GENERAL NOTES

DPZO-A\* proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components.

The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

# 6 OPTIONS FOR -A EXECUTION

6.1 Option /6 6 Vbc coil instead of standard 12 Vbc, to be used in case of power supply 12 Vbc

6.2 Option /18 18 Vpc coil instead of standard 12 Vpc, to be used with electronic drivers not supplied by Atos

# 7 CONNECTIONS FOR -A EXECUTION

	SOLENOID POWER SUPPLY CONNECTOR							
PIN	Signal description							
1	SUPPLY							
2	SUPPLY							
3	GND							

#### 8 ANALOG INTEGRAL DRIVERS -AE - OPTIONS

Standard driver execution provides on the 7 pin main connector:

 Power supply
 - 24Vbc must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to the driver power supply. Apply at least a 10000 μF/40 V capacitance to single phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers
 Reference input signal
 - analog differential input with ±10 Vbc nominal range (pin D,E), proportional to desired coil current.

Monitor output signal - analog output signal proportional to the actual valve's coil current (1V monitor = 1A coil current)

Following options are available to adapt standard execution to special application requirements:

#### 8.1 Option /I

It provides the 4+20 mA current reference signal instead of the standard ±10 Vbc. Monitor output signal is still the standard ±10 Vbc.

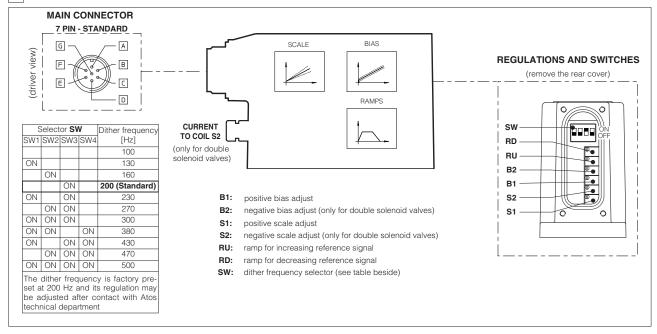
It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

8.2 Option /Q

It provides the possibility to enable or disable the valve functioning without cutting the power supply (the valve functioning is disabled but the driver current output stage is still active). To enable the driver supply a 24Vbc on the enable input signal.

#### 8.3 Possible combined options: /IQ

# 9 ANALOG INTEGRAL DRIVERS - AE - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



## 9.1 ELECTRONIC CONNECTIONS - 7 PIN MAIN CONNECTORS

PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
A	V+	Power supply 24 Vbc for solenoid power stage and driver logic	Input - power supply
В	VO	Power supply 0 Vbc for solenoid power stage and driver logic	Gnd - power supply
C <sup>(1)</sup>	AGND	Ground - signal zero for MONITOR signal	Gnd - analog signal
	ENABLE	Enable (24 VDc) or disable (0 VDc) the driver (for /Q option)	Input - on/off signal
D	INPUT+	Reference analog differential input: ±10 Vpc maximum range (4 ÷ 20 mA for /l option) Default setting for single solenoid valves: 0++10 Vpc	Input - analog signal
E	INPUT -	Default setting for double solenoid valves: ±10 Vpc	
F	MONITOR	Monitor analog output: ±5 Vpc maximum range; 1 V = 1 A	Output - analog signal
G	EARTH	Internally connected to the driver housing	

Note: (1) with /Q option ENABLE signal replaces AGND on pin C; MONITOR signal is referred to pin B.

A minimum time of 60ms to 160ms have be considered between the driver energizing with the 24 Vbc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

# 10 DIGITAL INTEGRAL DRIVERS -AES - OPTIONS

Standard driver execution provides on the 7 pin main connector:

Power supply
 - 24Vbc must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to each driver power supply Apply at least a 10000 μF/40 V capacitance to single phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers.

Reference input signal - analog differential input with ±10Vpc nominal range (pin D,E), proportional to desired coil current (4÷20 mA with cable break detection, ±10 mA, ±20 mA or 0÷20 mA software selectable)

Monitor output signal - analog output signal proportional to the actual valve's coil current (1V monitor = 1A coil current)

Following options are available to adapt standard execution to special application requirements:

#### 10.1 Option /Q

To enable the driver, supply 24Vdc on pin C referred to pin B: when the enable signal is set to zero the valve status is software selectable, by factory default the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active. For the complete list of selectable status, see tab. G115.

#### 10.2 Option /Z

It provides, on the 12 pin main connector, the following additional features:

#### Logic power supply

Separated power supply for the solenoid (pin 1, 2) and for the digital electronic circuits (pin 9, 10).

Cutting solenoid power supply allows to interrupt the valve functioning but keeping energized the digital electronics thus avoiding fault conditions of the machine fieldbus controller. This condition allows to realize safety systems in compliance with European Norms EN13849-1 (ex EN954-1).

#### **Enable Input Signal**

To enable the driver, supply 24Vdc on pin 3 referred to pin 2: when the enable signal is set to zero the valve status is software selectable, by factory default the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active. For the complete list of selectable status, see tab. G115.

# Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4÷20mA input, etc.). Fault presence corresponds to 0 Vpc, normal working corresponds to 24Vpc (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

**10.3 Option /W** - only for valves coupled with pressure compensator type HC-011 or KC-011 (see tab. D150). It provides, on the 12 pin main connector, the above option /Z features plus the hydraulic power limitation function.

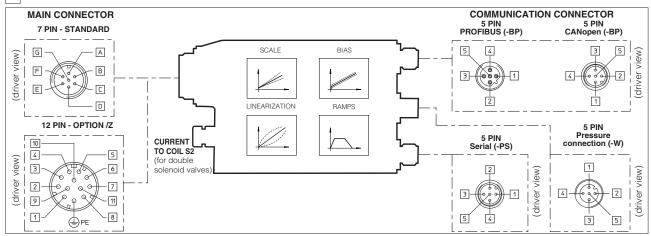
The driver receives the flow reference signal by the analog external input INPUT+ and a pressure transducer remotely installed in the hydraulic system, has to be connected to the driver's analog input TR.

When the actual requested hydraulic power  $\mathbf{p} \times \mathbf{Q}$  (TR x INPUT+) reaches the max power limit (p1xQ1), internally set by software, the driver automatically reduces the flow regulation of the valve. The higher is the pressure feedback the lower is the valve's regulated flow:

Transducer Pressure [TR]

#### For detailed information on hydraulic power limitation, see tab. G115

## 11 DIGITAL INTEGRAL DRIVERS - AES - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



#### 11.1 ELECTRONIC CONNECTIONS - 7 & 12 PIN MAIN CONNECTORS (-AES standard, /Q, /Z, /W options)

Standard 7pin	/Z, /W options 12pin	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
A	1	V+	Power supply 24 Vbc for solenoid power stage (and for driver logic on 7 pin connection)	Input - power supply
В	2	VO	Power supply 0 Vbc for solenoid power stage (and for driver logic on 7 pin connection)	Gnd - power supply
C (option /Q)	3	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver	Input - on/off signal
D	4	INPUT+	Reference analog input: ±10 Vbc ±20 mA maximum range software selectable	
E	-	INPUT -	Default setting for single solenoid valves: 0÷+10 Vpc, differential input Default setting for double solenoid valves: ±10 Vpc, differential input /Z and /W options: common mode INPUT+ referred to AGND	Input - analog signal
С	5	AGND	Ground - signal zero for MONITOR signal (INPUT+ signal only for /Z and /W options)	Gnd - analog signal
F	6	MONITOR	Monitor analog output: ±5 Vpc maximum range; Default setting 1V = 1A	Output - analog signal
-	7	NC	do not connect	
-	8	MONITOR 2	2nd monitor analog output: ±5 Vpc maximum range (only for /W option)	Output - analog signal
-	9	VL+	Power supply 24 Vbc for driver logic	Input - power supply
-	10	VL0	Power supply 0 Vpc for driver logic	Gnd - power supply
-	11	FAULT	Fault (0 Vbc) or normal working (24 Vbc)	Output - on/off signal
G	PE	EARTH	Internally connected to the driver housing	

Note: A minimum time of 270 to 340 ms have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

# 11.2 ELECTRONIC CONNECTIONS - 5 PIN COMMUNICATION AND PRESSURE TRANSDUCER CONNECTORS

	-PS Serial		-BC CANopen		-	BP PROFIBUS DP	/W option		
PIN	SIGNAL	TECHNICAL SPECIF.	SIGNAL	TECHNICAL SPECIF.	SIGNAL	TECHNICAL SPECIF.	SIGNAL	TECHNICAL SPECIF.	
1	NC	do not connect	CAN_SHLD	Shield	+5V	for termination	VT trans	ducer power supply 24 Vbc	
2	NC	do not connect	NC	do not connect	LINE-A	Bus line (high)	TR tran	sducer signal 0÷10 Voc	
3	RS_GND	Signal zero data line	CAN_GND	Signal zero data line	DGND	Data line and termination Signal zero	AGND	Signal zero for power supply and signal	
4	RS_RX	Receiving data line	CAN_H	Bus line (high)	LINE-B	Bus line (low)	NC	do not connect	
5	RS_TX	Transmitting data line	CAN_L	Bus line (low)	SHIELD	do not connect	NC	do not connect	

# 12 SOFTWARE TOOLS

The driver configuration and parameters can be easily set with the Atos E-SW programming software, available in three different versions according to the driver's communication execution: E-SW-PS (Serial), E-SW-BC (CANopen) and E-SW-BP (PROFIBUS DP). Programming software E-SW-BC and E-SW-BP, for BC and BP drivers, can be also used to modify the valve's parameterization through the serial communication interface, without disconnecting the valve from the machine's bus line.

For a more detailed description of software interface, PC requirements, adapters, cables and terminators, please refer to technical table G500.

Programming software, must be ordered separately: E-SW-\* (mandatory - first supply) = Dvd including E-SW-\* software installer and operator manuals; it allows the registration to Atos digital service E-SW-\*-N (optional - next supplies) = as above but not allowing the registration to Atos digital service On first supply of the E-SW-\* software, it is required to apply for the registration in the Atos download area: www.download.atos.com.

Once the registration is completed, the password will be sent by email.

The software remains active for 10 days from the installation date and then it stops until the user inputs his password.

With the password you can also download, in your personal area, the latest releases of the Atos software, manuals, drivers and configuration files.

# 13 MAIN CHARACTERISTICS OF PROPORTIONAL DIRECTIONAL VALVES

Assembly position	Any position								
Subplate surface finishing	Roughness index, $\sqrt{^{0.4}}$ flatness ra	Roughness index, $\sqrt{^{04}}$ flatness ratio 0,01/100 (ISO 1101)							
Ambient temperature	-20°C ÷ +70°C for -A execution; -2	-20°C ÷ +70°C for -A execution; -20°C ÷ +60°C for -AE, -AES, -AEG and -AEZ executions							
Fluid	Hydraulic oil as per DIN 51524	Hydraulic oil as per DIN 51524 535 for other fluids see section 1							
Recommended viscosity	Disity 15 ÷100 mm²/s at 40°C (ISO VG 15÷100)								
Fluid contamination class	ISO 18/15 achieved with in line filte	ISO 18/15 achieved with in line filters of 10 $\mu$ m and $\beta_{10} \ge 75$ (recommended)							
Fluid temperature	-20°C +60°C (standard and /WG s	-20°C +60°C (standard and /WG seals) -20°C +80°C (/PE seals)							
Coil voltage	12 Vbc coil	6 Vpc coil	18 Vpc coil						
Coil resistance R at 20°C	3 ÷ 3,3 Ω	2÷2,2 Ω	$13 \div 13,4 \Omega$						
Max. solenoid current	1,9 A	2,35 A	0,9 A						
Max. power		30 Watt							
Protection degree (CEI EN-60529)	IP65 for -A execution; IP67 for -AE, -A	AES, -AEG and -AEZ executions							
Duty factor Continuous rating (ED=100%)									

## 14.1 Regulation diagrams

DPZO-1: 1 = linear spool L5 **2** = differential spool S5, D5 DPZO-2: **3** = progressive spool S3, D3 **4** = progressive spool S5, D5 5 = linear spool L5 DPZO-3: 6 = linear spool 15 7 = progressive spool S5, D5 DPZO-6: 8 = linear spool L5 9 = progressive spool S5, D5

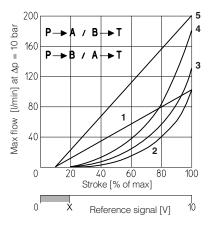
#### Note:

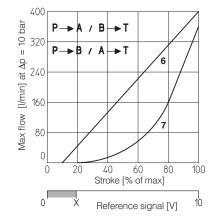
Hydraulic configuration vs reference signal for: - double solenoid valves (standard and option /B)

Reference signal 
$$0 \div +10 V$$
  
 $12 \div 20 \text{ mA}$   $P \rightarrow A / B \rightarrow T$   
Reference signal  $0 \div -10 V$   
 $P \rightarrow B / A \rightarrow T$ 

 $4 \div 12 \text{ mA}$   $P \rightarrow B / A$ Hydraulic configuration vs reference signal for single solenoid valves:

$$\begin{array}{c} 0 \div +10 \text{ V} \\ 4 \div 20 \text{ mA} \end{array} \right\} \begin{array}{c} P \rightarrow A \ / \ B \rightarrow T \ (\text{standard}) \\ P \rightarrow B \ / \ A \rightarrow T \ (\text{option} \ / B) \end{array}$$





 $\mathbf{X}$  = Threshold for bias activation depending to the valve type and amplifier type

2

Þ.

P В

Valve pressure drop ∆p [bar]

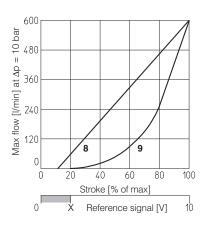
70 100

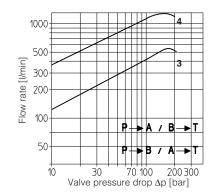
30

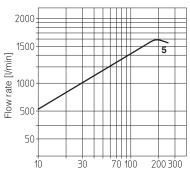
1

200 300

B -≽|T





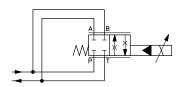


Valve pressure drop ∆p [bar]

# 14.3 Operation as throttle valve

Single solenoid valves (\*51) can be used as simple throttle valves: Pmax = 250 bar

For this application, the use of valve -T, -TE or -TES (see tab. F172 and F175) is advisable (consult our technical office)



1000

500

300

200

100

50

10

Flow rate [I/min]

DPZC	)-*-	151-L5	251-L5	351-L5	651-L5
Max flow	[l/min]	320	650	1300	2000
Δр	[bar]	30	30	30	30

# 14.2 Flow /Ap diagram

Stated at 100% of valve stroke

DPZO-1: 1 = spool L5, S5, D5 DPZO-2:

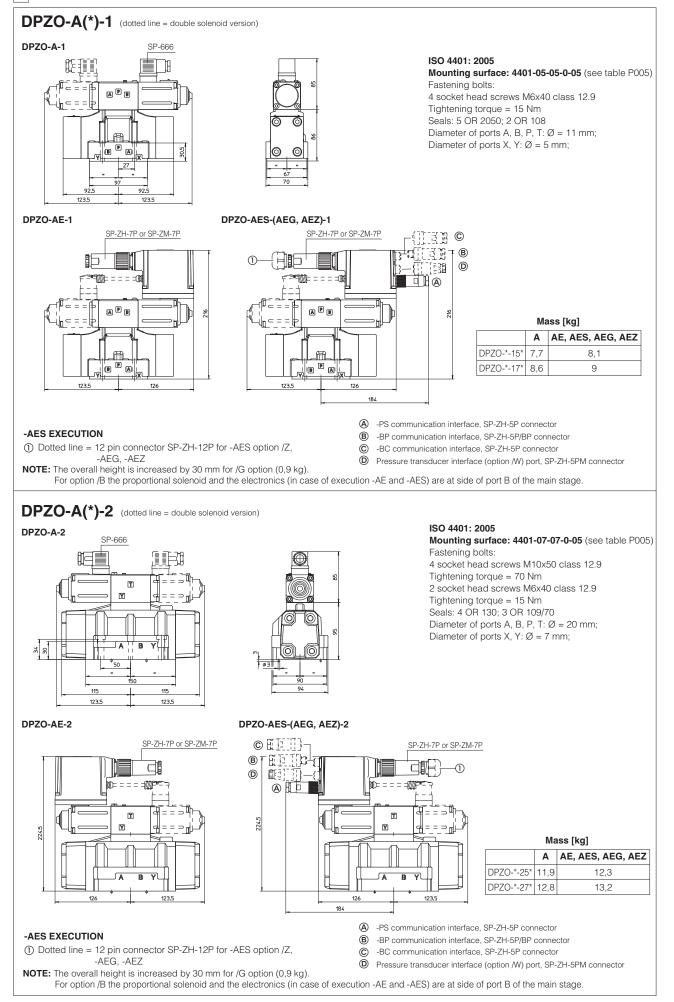
**2** = spool L5, S5, D5 **3** = spool S3, D3

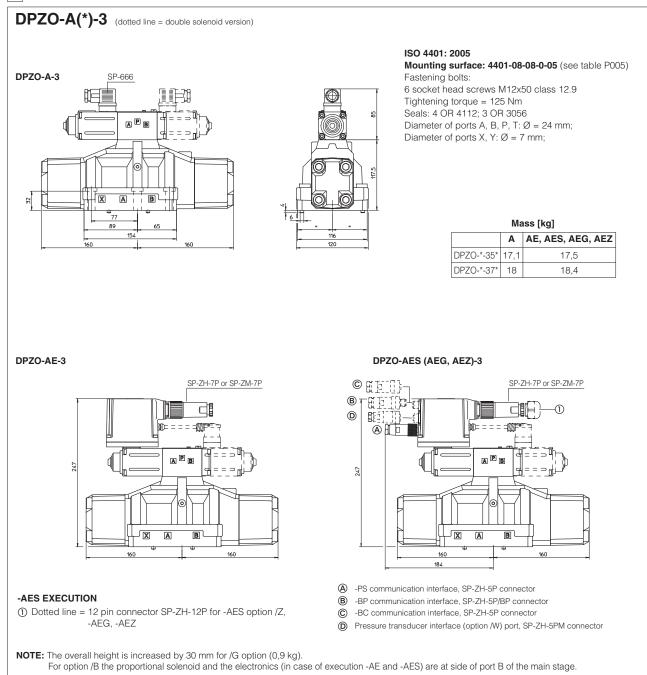
DPZO-3: 4 = spool L5, S5, D5

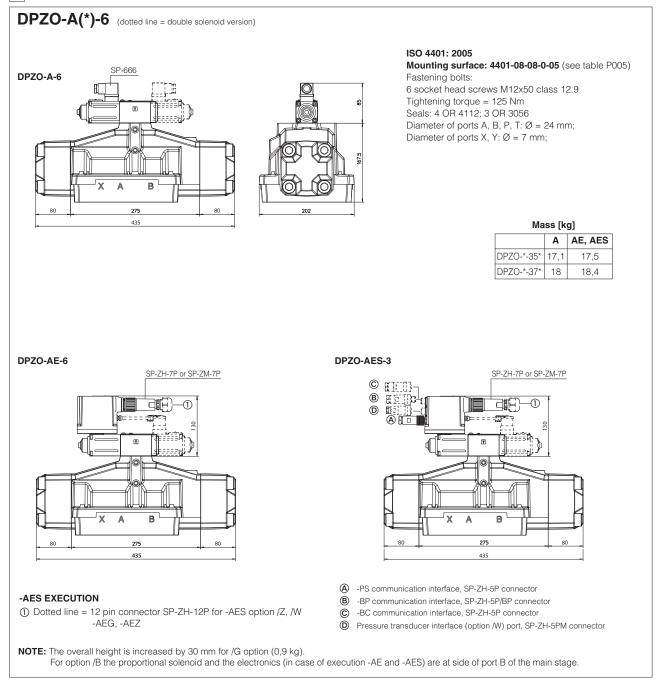
DPZO-6: **5** = spool L5, S5, D5



# 15 INSTALLATION DIMENSIONS FOR DPZO-1 AND DPZO-2 [mm]







# 18 MODEL CODES OF POWER SUPPLY AND COMMUNICATION CONNECTORS (to be ordered separately)

VALVE VERSION	-A	-AE, -AES		-AES/Z -/W -AEG -AEZ	-AES/W (transducer)	-Serial (-PS) or CANopen (-BC)	PROFIBUS DP (-BP)
CONNECTOR CODE	SP-666	SP-ZH-7P	SP-ZM-7P	SP-ZH-12P	SP-ZH-5PM	SP-ZH-5P	SP-ZH-5P/BP
PROTECTION DEGREE	IP65	IP67	IP67	IP67	IP67	IP67	IP67
DATA SHEET	K500		G110, G115	G115	i, K500		

connectors supplyed with the valve